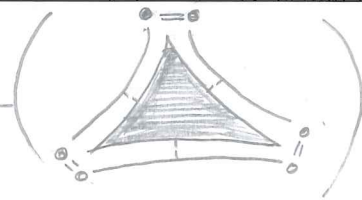


CAT 3

Homology



Quest 0

Find computable homotopy-invariants of simplicial complexes — these are assignments of the form

$$K \mapsto I(K)$$

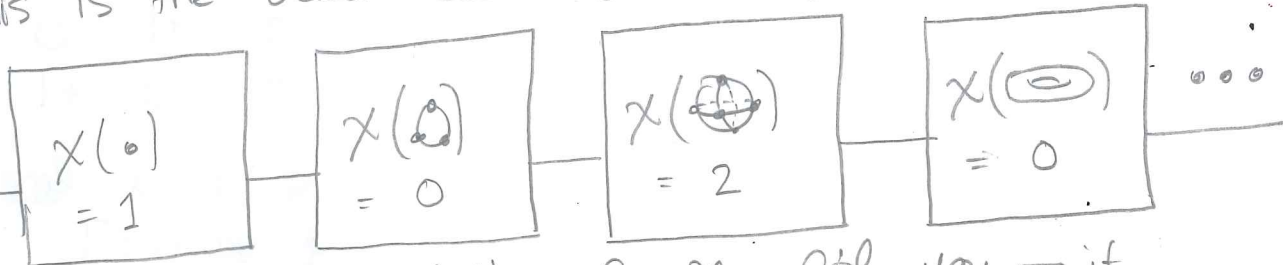
of algebraic objects $I(K)$ to simplicial complexes K so that if K and L are homotopy-equivalent then $I(K)$ and $I(L)$ are "equal".

Def 1

The EULER CHARACTERISTIC of a finite simplicial complex K is the alternating simplex count

$$\chi(K) = \sum_{i=0}^{\dim K} \# \{ \sigma \in K \mid \dim \sigma = i \}$$

This is the oldest interesting topological invariant.



Note 2

Don't let the simplicity of χ fool you — it conceals several important and fascinating properties, as we will see later in this course. For one thing, χ is a homotopy invariant, eg

$$\chi(\bigcirc) = \chi(\bigotimes)$$

Eg 3

- A number $k \in \mathbb{Z}_{>0}$ is called SQUAREFREE if \nexists prime p so that p^2 divides k .
- For each such k , let $\pi(k) = \{ \text{list of primes dividing } k \}$. Note that this list is closed under taking subsets.
- Now $\forall n \in \mathbb{Z}_{>0}$ define $K_n = \{ \pi(k) \mid k \leq n \text{ is squarefree} \}$

This forms a simplicial complex [the i -dim'l simplices are lists of length = $i-1$].

So now we have a sequence of Euler characteristics: $\chi(K_1), \chi(K_2), \chi(K_3), \dots$ one for each n .

Thm [A Björner 2011]

$$\chi(K_n) \in O(n^{1/2+\epsilon}) \quad \forall \epsilon > 0$$

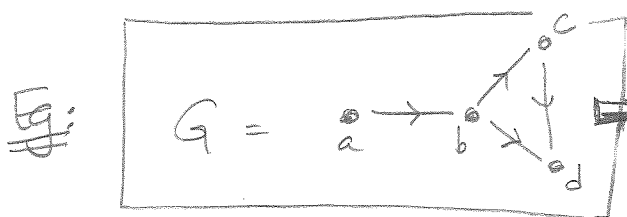


Riemann Hypothesis

CHAIN COMPLEXES

Note 4

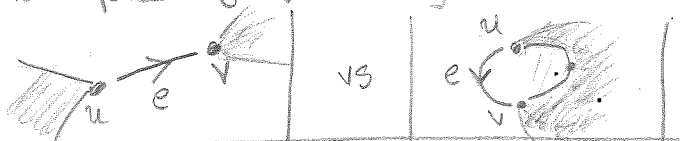
Directed graphs have "incidence matrices" which record connections between vertices and edges:



$$I_G = \begin{matrix} & \begin{matrix} ab & bc & bd & cd \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} -1 & 0 & 0 & 0 \\ +1 & -1 & -1 & 0 \\ 0 & +1 & 0 & -1 \\ 0 & 0 & +1 & +1 \end{bmatrix} \end{matrix}$$

What does this MEAN? Well, this is a linear map [vector space of edges] \rightarrow [vector space of vertices] that sends each $(u \xrightarrow{e} v)$ to $\underbrace{v-u}$.

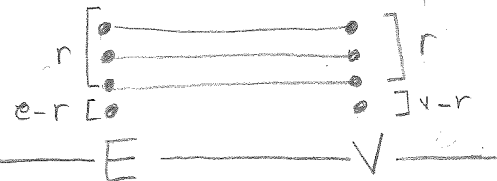
"algebraic boundary"



Prop 5

Let G be a finite directed graph with v vertices, e edges and incidence matrix I_G of rank r . Then,

$$\begin{aligned} \# [\text{components of } G] &= v - r \\ \# [\text{loops in } G] &= e - r \end{aligned}$$



Def 6 a)

By an "orientation" of a simplicial complex K we mean an ordering of all the vertices, i.e., an injective map $K_0 \rightarrow \mathbb{N}$. [This is the simplicial version of a directed graph]. We always write $\sigma = (v_0, \dots, v_n)$ in order.

b) Let K be an oriented simplicial complex. The ALGEBRAIC BOUNDARY of an n -simplex $\sigma = (v_0, \dots, v_n)$ is the following linear combination of $(n-1)$ simplices:

$$\partial_n \sigma = \sum_{i=0}^n (-1)^i (v_0, \dots, \cancel{v_i}, \dots, v_n)$$

Eg:

$$\partial_1 (a \text{---} b) = b - a \quad \text{and} \quad \partial_2 (\triangle_{abc}) = \begin{array}{c} c \\ \diagdown \quad \diagup \\ a \quad b \end{array} = \begin{array}{c} c \\ \diagdown \\ b \end{array} - \begin{array}{c} c \\ \diagup \\ a \end{array} + \begin{array}{c} \text{---} \\ a \quad b \end{array}$$

Prop? For any n -simplex $\sigma = (v_0, \dots, v_n)$ in an oriented simplicial complex K , we have

$$\partial_{n-1} \circ \partial_n (\sigma) = 0$$

Try $n=2$; now $\sigma = (a, b, c)$. We get

$$\partial_1 \partial_2 (\triangle_{abc}) = \partial_1 \left(\begin{array}{c} c \\ \diagdown \quad \diagup \\ a \quad b \end{array} \right) = \partial_1 \left(\begin{array}{c} c \\ \diagdown \\ b \end{array} - \begin{array}{c} c \\ \diagup \\ a \end{array} + \begin{array}{c} \text{---} \\ a \quad b \end{array} \right)$$

Here we have extended ∂_1 from simplices to linear combinations by linearity...

$$\begin{aligned} &= \partial_1 \left(\begin{array}{c} c \\ \diagdown \\ b \end{array} \right) - \partial_1 \left(\begin{array}{c} c \\ \diagup \\ a \end{array} \right) + \partial_1 \left(\begin{array}{c} \text{---} \\ a \quad b \end{array} \right) \\ &= \left(\begin{array}{c} c \\ \diagdown \\ b \end{array} - \begin{array}{c} c \\ \diagdown \\ a \end{array} \right) - \left(\begin{array}{c} c \\ \diagup \\ a \end{array} - \begin{array}{c} c \\ \diagup \\ b \end{array} \right) + \left(\begin{array}{c} \text{---} \\ b \quad a \end{array} \right) \end{aligned}$$

$$= 0$$

Now we have to extend this reasoning to $n > 2 \dots$ everything occurs twice, but with opposite signs!

Problem Sheet 2

Note 8

So if you hand me an oriented simplicial complex of top dimension n , I can build a sequence of vector spaces and linear maps of the form

$$C_n^k \xrightarrow{\partial_n^k} C_{n-1}^k \xrightarrow{\partial_{n-1}^k} \dots \xrightarrow{\partial_2^k} C_2^k \xrightarrow{\partial_2^k} C_1^k \xrightarrow{\partial_1^k} C_0^k$$

With the property that composing any adjacent pair $\partial_{i-1} \circ \partial_i$ of these maps yields zero, $C_i \rightarrow C_{i-2}$.

Let's use \mathbb{Q} coeffs here.

Here C_i^k is the vector space generated by all the oriented i -simplices. To make this precise, we must choose COEFFICIENTS, eg \mathbb{R} or \mathbb{Q} or \mathbb{Z}/p , to fully define scalar multiplication beyond ± 1 .

Def 9
a)

A CHAIN COMPLEX is a sequence of vector spaces and linear maps of the form:

$$\boxed{\dots \xrightarrow{d_3} C_2 \xrightarrow{d_2} C_1 \xrightarrow{d_1} C_0 \rightarrow 0}$$

(this can keep going)

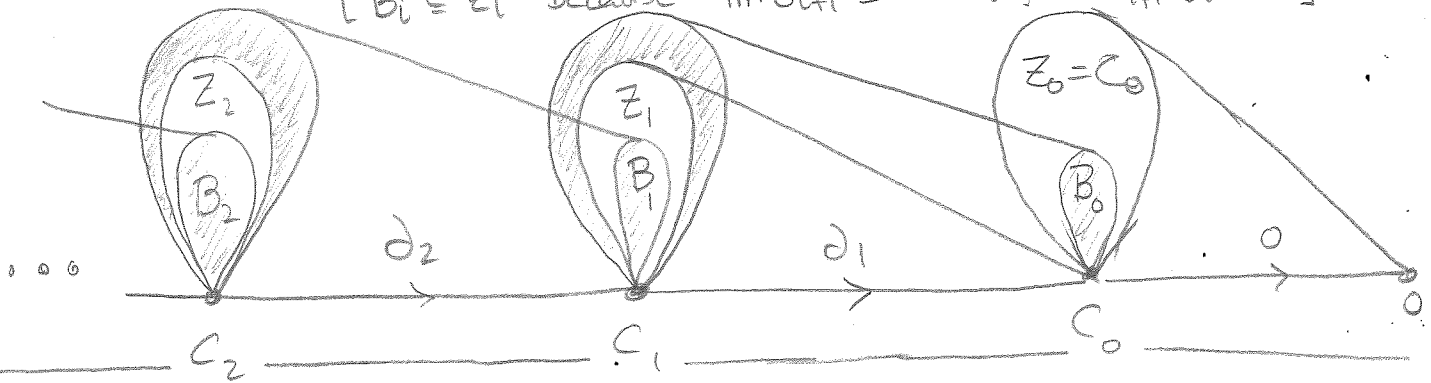
$C_i =$ space of i -chains

so that $d_{i-1} \circ d_i = C_i \rightarrow C_{i-2}$ is the zero map for all $i > 0$. [Write this as (C_\bullet, d_\bullet)]

b)

The vector space of i -CYCLES is the subspace $Z_i \subseteq C_i$ given by $\ker d_i$. And the vector space of i -BOUNDARIES $B_i \subseteq C_i$ is the image $\text{im } d_{i+1}$:

$$[B_i \subseteq Z_i \text{ because } \text{im } d_{i+1} \subseteq \ker d_i \iff d_{i+1} \circ d_i = 0]$$



Def 10

The HOMOLOGY GROUPS of a chain complex (C_\bullet, d_\bullet) are defined to be the quotients

$$H_i = Z_i / B_i$$

of cycle-spaces by boundary spaces. [So H_i is a SUB-QUOTIENT of C_i , i.e.: the quotient of a subspace]

Note 11

The HOMOLOGY OF A SIMPLICIAL COMPLEX K is defined to be the homology of its chain complex $(C_\bullet^k, d_\bullet^k)$ [from Note 8]. It is denoted $H_i(K)$, or when

We want to emphasize the chosen field of coefficients $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{Z}/p, \dots\}$, we write it as $H_i(K; \mathbb{F})$.

Ex 12
a)

$$H_i(\text{point}; \mathbb{F}) = \begin{cases} \mathbb{F}, & i=0 \\ 0, & \text{otherwise} \end{cases}$$

The chain complex is $\left[\cdots \rightarrow 0 \rightarrow \cdots \rightarrow 0 \rightarrow \mathbb{F} \rightarrow 0 \right]$

b)

$$H_i(\triangle) = \begin{cases} \mathbb{F}, & i=0 \text{ or } 1 \\ 0, & \text{otherwise} \end{cases}$$

The chain complex is $\left[\cdots \rightarrow 0 \rightarrow \cdots \rightarrow \mathbb{F}^3 \xrightarrow{\alpha} \mathbb{F}^3 \rightarrow 0 \right]$
where α is a 3×3 matrix of rank 2.

Facts
13

A Homology is a FUNCTOR: not only does it attach vector spaces $H_i(K; \mathbb{F})$ to simplicial complexes K , but it also assigns linear maps $H_i f: H_i(K) \rightarrow H_i(L)$ to simplicial maps $f: K \rightarrow L$. (More on this later)

B Homology is a homotopy-invariant. So, if K and L are homotopy-equivalent then $H_i(K; \mathbb{F})$ and $H_i(L; \mathbb{F})$ are isomorphic (regardless of i and \mathbb{F})

C Computing Homology of finite simplicial complexes is possible via standard Gaussian elimination of matrix representations of d_n^K 's.

D Euler characteristic inherits its homotopy invariance from homology:
$$\chi(K) = \sum_{i=0}^{\dim K} (-1)^i \dim H_i(K; \mathbb{F})$$

More on Computations of Homology...

It is important to note that over any FIELD, the computation of homology reduces to computing ranks of all the d_i 's. [Things are more complicated over \mathbb{Z}].

Prop 14

Let K be a simplicial complex (finite, of course!)
 If $n_i = \# \{i\text{-simplices in } K\}$ is $\dim C_i^K$, and
 if $r_i = \text{rank}(d_i^K)$, then:

$$\dim H_i(K) = n_i - (r_i + r_{i+1})$$

[Note $\dim Z_i = n_i - r_i$ and $\dim B_i = r_{i+1}$]

Note 15

a)

Really, we are DIAGONALIZING all the d_i 's. As we have assumed field coefficients, this means for each d_i there are INVERTIBLE MATRICES P_i and Q_i so that

$$d_i = P_i \left[\begin{array}{ccc|ccc} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ \hline & & & & & \\ 0 & & & & & \\ & & & & 0 & \\ & & & & & 0 \end{array} \right] Q_i$$

$(n_i \times n_i)$ $(n_{i+1} \times n_{i+1})$

(Note: An arrow points from the '1' in the diagonal to the '0' in the bottom-right corner of the matrix.)

This diagonal matrix is called the SMITH NORMAL FORM of d_i , and it looks more interesting over \mathbb{Z} -coefficients

b)

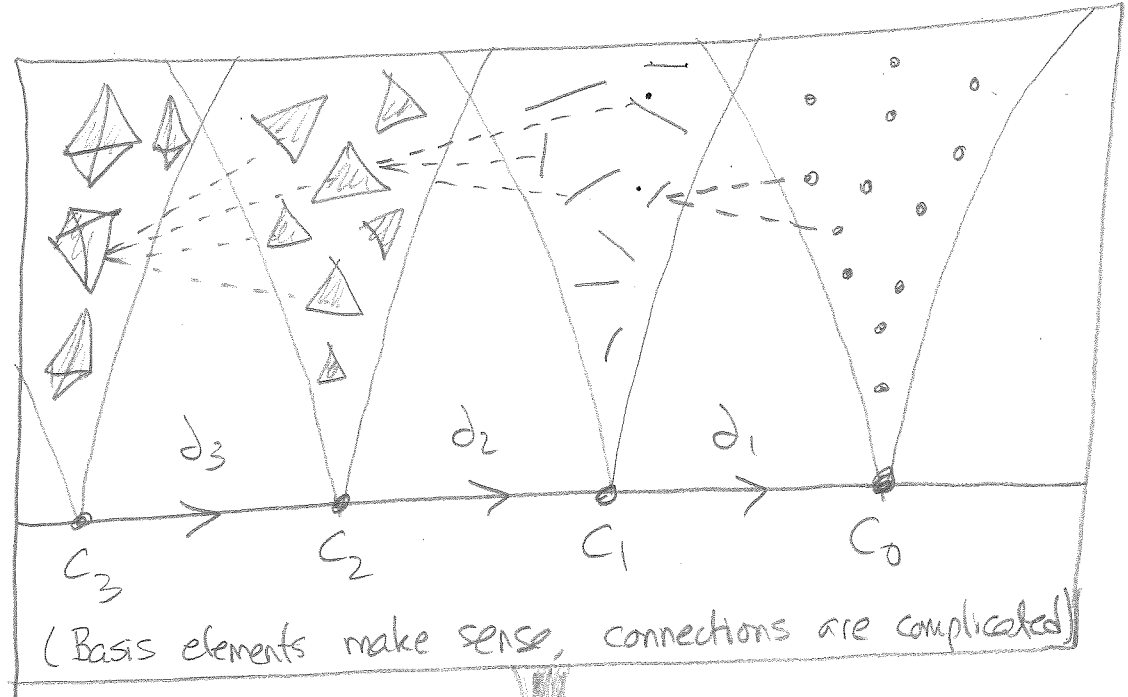
Algorithmically, going from d_i to its SNF "just" amounts to using row operations to get pivot columns [this produces a change-of-basis matrix P_i] and then column operations to get pivot rows [this produces Q_i]. You can do both row and column ops at once, of course but... SNF!

$$\begin{bmatrix} * & * & * & * & * \\ * & * & & & \\ * & * & * & * & * \\ * & * & * & * & * \end{bmatrix} \xrightarrow{P_i \cdot [d_i]} \begin{bmatrix} 1 & * & 0 & \dots & * \\ 0 & 0 & 1 & * & * \\ \vdots & & & & \\ 0 & \dots & 0 & & \end{bmatrix} \xrightarrow{P_i \cdot Q_i} \begin{bmatrix} 1 & 0 & & & 0 \\ 0 & 1 & & & 0 \\ \vdots & & \ddots & & \\ 0 & & & 1 & \\ 0 & & & & 0 \end{bmatrix}$$

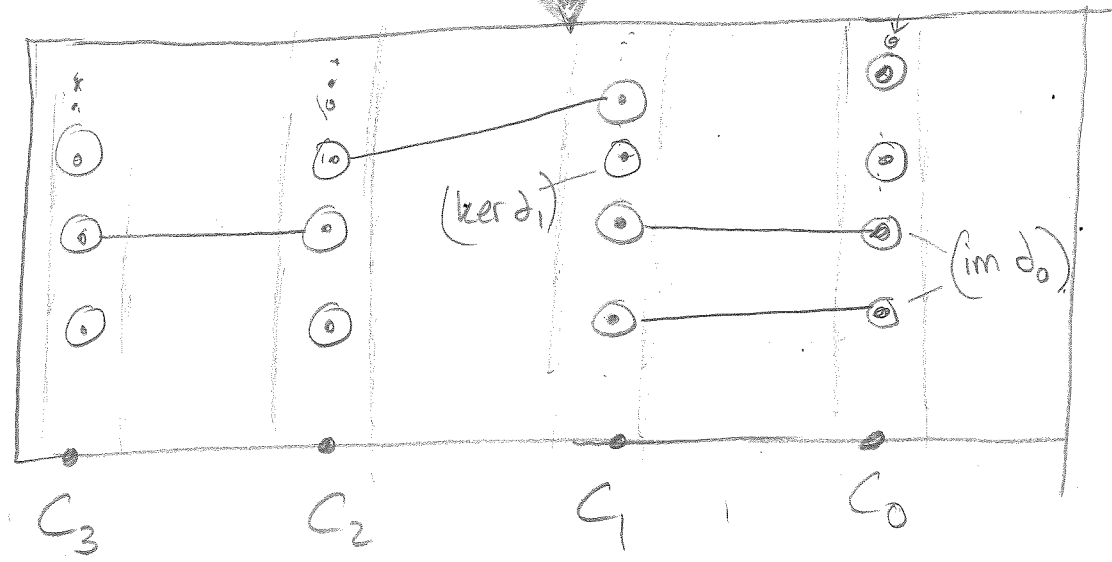
Pic 16

There's a SINGLE PICTURE to keep in mind when going from chain complexes to homology groups via matrix diagonalization. It often gets lost in the algebraic noise, but I hope you will remember.

DIAGONALIZING $[d_i]$ TURNS THIS:



↓ INTO THIS



Here each \odot is a weird linear combination of i -simplices, the number of "lines" from C_0 to C_{i-1} is the rank of d_i , and the UN-LINED \odot 's count $\dim H_i$.